Supplementary Material for Integrated Low Rank Based Discriminative Feature Learning for Recognition

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I. PROOF OF THEOREM 3.2

Before we prove Theorem 3.2, we introduce a lemma, which is described as follows.

Lemma 1.1 ([1], [2]): Suppose that $f : \mathbb{R}^m \to \mathbb{R}$ is a continuously differentiable function with Lipschitz continuous gradient whose Lipschitz constant is L. Then for any $x, y \in \mathbb{R}^m$ and $\gamma \ge L$,

$$f(x) \le f(y) + \langle x - y, \nabla f(y) \rangle + \frac{\gamma}{2} ||x - y||_2^2.$$
(1)

1

Now, we prove Theorem 3.2.

proof Let $f(Q_i) = \|\tilde{H}_i - Q_i\|_2^2$ $(i = 1, \dots, r)$. It is easy to check that $f(Q_i)$ satisfies Lemma 1.1, $\nabla f(Q_i) = -2(\tilde{H}_i - Q_i)$ and L = 2. We first prove the following inequality:

$$\langle Q_i^{k+1} - Q_i^k, \nabla f(Q_i^k) \rangle + \frac{\gamma}{2} \|Q_i^{k+1} - Q_i^k\|_2^2 + \frac{\alpha}{(g_i^k)^2} \|Q_i^{k+1}\|_2^2 \le \frac{\alpha}{(g_i^k)^2} \|Q_i^k\|_2^2, \quad (\forall k, i),$$

$$\tag{2}$$

where k denotes the number of iterations. Define $\beta_k = \frac{(g_i^{k-1})^2}{(g_i^{k-1})^2 + \alpha}$, then $Q_i^k = \frac{(g_i^{k-1})^2}{(g_i^{k-1})^2 + \alpha}\tilde{H}_i = \beta_k\tilde{H}_i$. We consider inequality (2).

$$\begin{aligned} c &= \langle Q_{i}^{k+1} - Q_{i}^{k}, \nabla f(Q_{i}^{k}) \rangle + \frac{\gamma}{2} \| Q_{i}^{k+1} - Q_{i}^{k} \|_{2}^{2} + \frac{\alpha}{(g_{i}^{k})^{2}} \| Q_{i}^{k+1} \|_{2}^{2} - \frac{\alpha}{(g_{i}^{k})^{2}} \| Q_{i}^{k} \|_{2}^{2} \\ &= \left\langle Q_{i}^{k+1} - Q_{i}^{k}, \nabla f(Q_{i}^{k}) + \frac{\gamma}{2} (Q_{i}^{k+1} - Q_{i}^{k}) + \frac{\alpha}{(g_{i}^{k})^{2}} (Q_{i}^{k+1} + Q_{i}^{k}) \right\rangle \\ &= \left\langle Q_{i}^{k+1} - Q_{i}^{k}, \left(2 - \frac{\gamma}{2} + \frac{\alpha}{(g_{i}^{k})^{2}}\right) Q_{i}^{k} + \left(\frac{\gamma}{2} + \frac{\alpha}{(g_{i}^{k})^{2}}\right) Q_{i}^{k+1} - 2\tilde{H}_{i} \right\rangle \\ &= (\beta_{k+1} - \beta_{k}) \left[\left(2 - \frac{\gamma}{2} + \frac{\alpha}{(g_{i}^{k})^{2}}\right) (\beta_{k} - \beta_{k+1}) + \left(\frac{\gamma}{2} + \frac{\alpha}{(g_{i}^{k})^{2}}\right) \beta_{k+1} - 2 \right] \| \tilde{H}_{i} \|_{2}^{2} \\ &= (\beta_{k+1} - \beta_{k}) \left[\left(2 - \frac{\gamma}{2} + \frac{\alpha}{(g_{i}^{k})^{2}}\right) (\beta_{k} - \beta_{k+1}) + 2 \frac{\alpha + (g_{i}^{k})^{2}}{(g_{i}^{k})^{2}} \beta_{k+1} - 2 \right] \| \tilde{H}_{i} \|_{2}^{2} \\ &= (\beta_{k+1} - \beta_{k}) \left[\left(2 - \frac{\gamma}{2} + \frac{\alpha}{(g_{i}^{k})^{2}}\right) (\beta_{k} - \beta_{k+1}) + 2 \frac{\alpha + (g_{i}^{k})^{2}}{(g_{i}^{k})^{2}} \frac{(g_{i}^{k})^{2}}{\alpha + (g_{i}^{k})^{2}} - 2 \right] \| \tilde{H}_{i} \|_{2}^{2} \\ &= (\beta_{k+1} - \beta_{k}) \left[\left(2 - \frac{\gamma}{2} + \frac{\alpha}{(g_{i}^{k})^{2}}\right) (\beta_{k} - \beta_{k+1}) + 2 \frac{\alpha + (g_{i}^{k})^{2}}{(g_{i}^{k})^{2}} \frac{(g_{i}^{k})^{2}}{\alpha + (g_{i}^{k})^{2}} - 2 \right] \| \tilde{H}_{i} \|_{2}^{2} \\ &= - (\beta_{k+1} - \beta_{k})^{2} \left(2 - \frac{\gamma}{2} + \frac{\alpha}{(g_{i}^{k})^{2}}\right) \| \tilde{H}_{i} \|_{2}^{2}. \end{aligned}$$

So if γ satisfies $L = 2 < \gamma \leq 4$, we have that $c \leq 0$, i.e., inequality (2) holds.

Note that g^{k+1} is the optimal solution to problem (4):

$$g^{k+1} = \underset{\sum_{i=1}^{r} g_i = t, g_i \ge 0}{\operatorname{argmin}} \sum_{i=1}^{r} \frac{\alpha}{g_i^2} \parallel Q_i^{k+1} \parallel_2^2.$$
(4)

So the following inequality holds.

$$\sum_{i=1}^{r} \frac{\alpha}{(g_i^k)^2} \|Q_i^{k+1}\|_2^2 \ge \sum_{i=1}^{r} \frac{\alpha}{(g_i^{k+1})^2} \|Q_i^{k+1}\|_2^2.$$
(5)

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Then, combining inequalities (2) and (5), we can further obtain the following inequality:

$$-\sum_{i=1}^{r} \langle Q_{i}^{k+1} - Q_{i}^{k}, \nabla f(Q_{i}^{k}) \rangle \geq \sum_{i=1}^{r} \left(\frac{\gamma}{2} \|Q_{i}^{k+1} - Q_{i}^{k}\|_{2}^{2} + \frac{\alpha}{(g_{i}^{k})^{2}} \|Q_{i}^{k+1}\|_{2}^{2} - \frac{\alpha}{(g_{i}^{k})^{2}} \|Q_{i}^{k}\|_{2}^{2} \right)$$
$$\geq \sum_{i=1}^{r} \left(\frac{\gamma}{2} \|Q_{i}^{k+1} - Q_{i}^{k}\|_{2}^{2} + \frac{\alpha}{(g_{i}^{k+1})^{2}} \|Q_{i}^{k+1}\|_{2}^{2} - \frac{\alpha}{(g_{i}^{k})^{2}} \|Q_{i}^{k}\|_{2}^{2} \right).$$
(6)

Since $f(Q_i)$ $(i = 1, \dots, r)$ satisfies Lemma 1.1, the following inequality holds:

$$\sum_{i=1}^{r} \left(f(Q_i^k) - f(Q_i^{k+1}) \right) \ge \sum_{i=1}^{r} \left(-\langle Q_i^{k+1} - Q_i^k, \nabla f(Q_i^k) \rangle - \frac{L}{2} \|Q_i^{k+1} - Q_i^k\|_2^2 \right) \\ \ge \sum_{i=1}^{r} \left(\frac{\alpha}{(g_i^{k+1})^2} \|Q_i^{k+1}\|_2^2 - \frac{\alpha}{(g_i^k)^2} \|Q_i^k\|_2^2 + \frac{\gamma - L}{2} \|Q_i^{k+1} - Q_i^k\|_2^2 \right).$$
(7)

Thus, we can obtain the following inequality:

$$F(Q^{k}, g^{k}) - F(Q^{k+1}, g^{k+1}) = \sum_{i=1}^{r} \left(f(Q_{i}^{k}) - f(Q_{i}^{k+1}) + \frac{\alpha}{(g_{i}^{k})^{2}} \|Q_{i}^{k}\|_{2}^{2} - \frac{\alpha}{(g_{i}^{k+1})^{2}} \|Q_{i}^{k+1}\|_{2}^{2} \right)$$

$$\geq \frac{\gamma - L}{2} \sum_{i=1}^{r} \|Q_{i}^{k+1} - Q_{i}^{k}\|_{2}^{2} = \frac{\gamma - L}{2} \|Q^{k+1} - Q^{k}\|_{F}^{2} \geq 0.$$
(8)

Therefore, $F(Q^k, g^k)$ is monotonically decreasing. So $F(Q^k, g^k) = \sum_{i=1}^r \left(\| \tilde{H}_i - Q_i^k \|_2^2 + \frac{\alpha}{(g_i^k)^2} \| Q_i^k \|_2^2 \right) \le F(Q^1, g^1)$. Thus $\{Q^k\}$ is bounded. Summing all the inequality (8) for all $k \ge 1$, we obtain

$$F(Q^{1}, g^{1}) - F(Q^{k+1}, g^{k+1}) \ge \frac{\gamma - L}{2} \sum_{j=1}^{k} \|Q^{j+1} - Q^{j}\|_{F}^{2}.$$
(9)

As $\gamma > L$, the above implies that $\lim_{k \to \infty} \|Q^{k+1} - Q^k\|_F^2 = 0$. As $g_i^k = \frac{t\|Q_i^k\|_2^{\frac{2}{3}}}{\sum\limits_{i=1}^r \|Q_i^k\|_2^{\frac{2}{3}}}$ $(\forall i = 1, \cdots, r), \lim_{k \to \infty} \|g^{k+1} - g^k\|_2^2 = 0$. As

 $\sum_{i=1}^{r} g_i = t > 0$ and $g_i \ge 0$, the sequence $\{g_k\}$ is bounded.

II. PROOF OF THEOREM 3.3

Proof In Theorem 3.2, we have proved that the sequence $\{Q^k, g^k\}$ is bounded. For any accumulation point (Q^*, g^*) of $\{Q^k, g^k\}$, suppose a subsequence (Q^{k_j}, g^{k_j}) fulfills $\lim_{j \to \infty} Q^{k_j} = Q^*$ and $\lim_{j \to \infty} g^{k_j} = g^*$. In each iteration, we denote

$$\tau^{k} = \frac{2\alpha}{t^{3}} \left(\sum_{i=1}^{r} \| Q_{i}^{k} \|_{2}^{\frac{2}{3}} \right)^{3}.$$
 (10)

Then there exists τ^* such that $\lim_{j\to\infty} \tau^{k_j} = \tau^*$. In our iteration process, $\nabla_Q F(Q^{k_j+1}, g^{k_j}) = 0$, $\nabla_g F(Q^{k_j+1}, g^{k_j+1}) + \tau^{k_j+1} = 0$, and $\sum_{i=1}^r g_i^{k_j} = t$. Letting $j \to \infty$, we have $\nabla_Q F(Q^*, g^*) = 0$, $\nabla_g F(Q^*, g^*) + \tau^* = 0$, and $\sum_{i=1}^r g_i^* = t$. So (Q^*, g^*) is a KKT point.

III. FAST ALGORITHM FOR ROBUST PCA [3]

In this section, we introduce the ℓ_1 -filtering for solving Robust PCA problem. We sketch it below.

 ℓ_1 -filtering first randomly samples a $s_r r \times s_c r$ submatrix X^s from X, where $s_r > 1$ and $s_c > 1$ are the row and column oversampling rates, respectively. For simplicity, we assume that X^s is at the top left corner of matrix X. Then accordingly X, A, and E is partitioned into:

$$X = \begin{bmatrix} X^s & X^c \\ X^r & \hat{X}^s \end{bmatrix}, \ A = \begin{bmatrix} A^s & A^c \\ A^r & \hat{A}^s \end{bmatrix}, \ E = \begin{bmatrix} E^s & E^c \\ E^r & \hat{E}^s \end{bmatrix},$$
(11)

where A is the low rank matrix we need to recover and E is the sparse error matrix.

Then ℓ_1 -filtering recovers A^s , called the seed matrix, from X^s by solving a small-sized Robust PCA problem. Since $s_r r$ and $s_c r$ are both small as compared with m and n, the computation of recovering A^s is much cheaper than recovering the whole A.

Next, as the rank of A and A^s are both r, there must exist matrix Q and P satisfying the following equations (12)

$$A^c = A^s Q, \quad A^r = P^T A^s.$$
⁽¹²⁾

Since the matrix E is sparse, the matrices E^c and E^r are also sparse. So we can find matrix Q and P by minimizing the following problems:

$$\min_{E^c,Q} \| E^c \|_1, \quad s.t. \ X^c = A^s Q + E^c, \tag{13}$$

and

$$\min_{E^r, P} \| E^r \|_1, \quad s.t. \; X^r = P^T A^s + E^r, \tag{14}$$

respectively. For these two problems, using the alternating direction method (ADM) [4] to solve them is efficient. So we can get P and Q, thus A^c and A^r can be also obtained. Finally, only \hat{A}^s needs to be computed. By the low-rankness of A, we can obtain

$$\hat{A}^s = P^T A^s Q. \tag{15}$$

In summary, the matrix A can be recovered with a complexity of $O(r^2(d+m))$ at each iteration [3], which is much lower than O(rmd) when d and m are large.

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